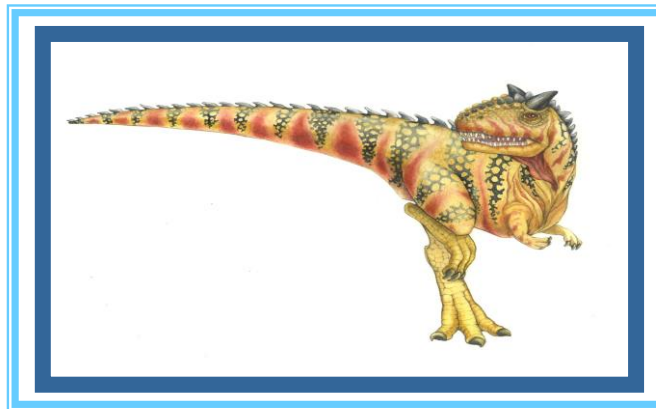


# Chapter 6: CPU Scheduling

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# Chapter 6: CPU Scheduling

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- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
- Sections from the textbook: 6.1, 6.2, and 6.3





# Objectives

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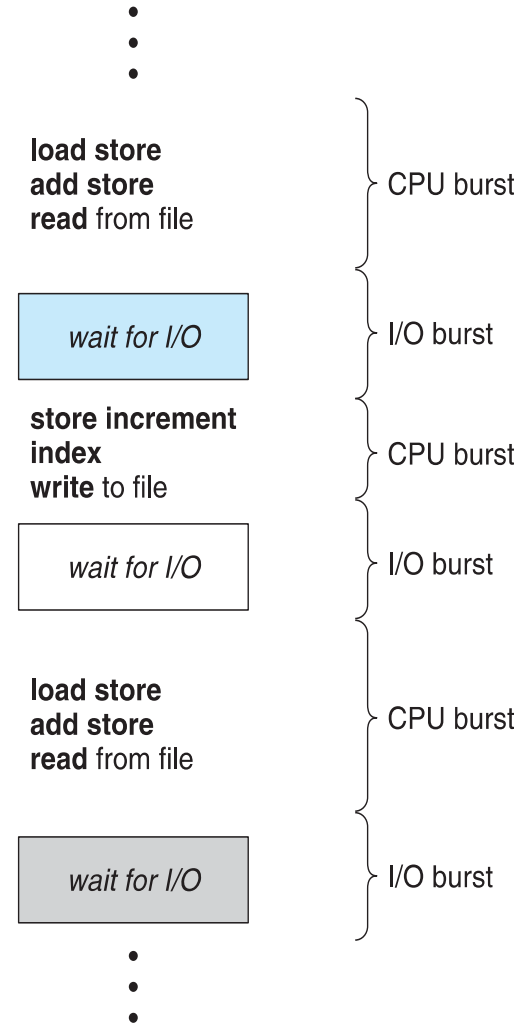
- To introduce CPU scheduling, which is the basis for multiprogrammed operating systems
- To describe various CPU-scheduling algorithms
- To discuss evaluation criteria for selecting a CPU-scheduling algorithm for a particular system





# Basic Concepts

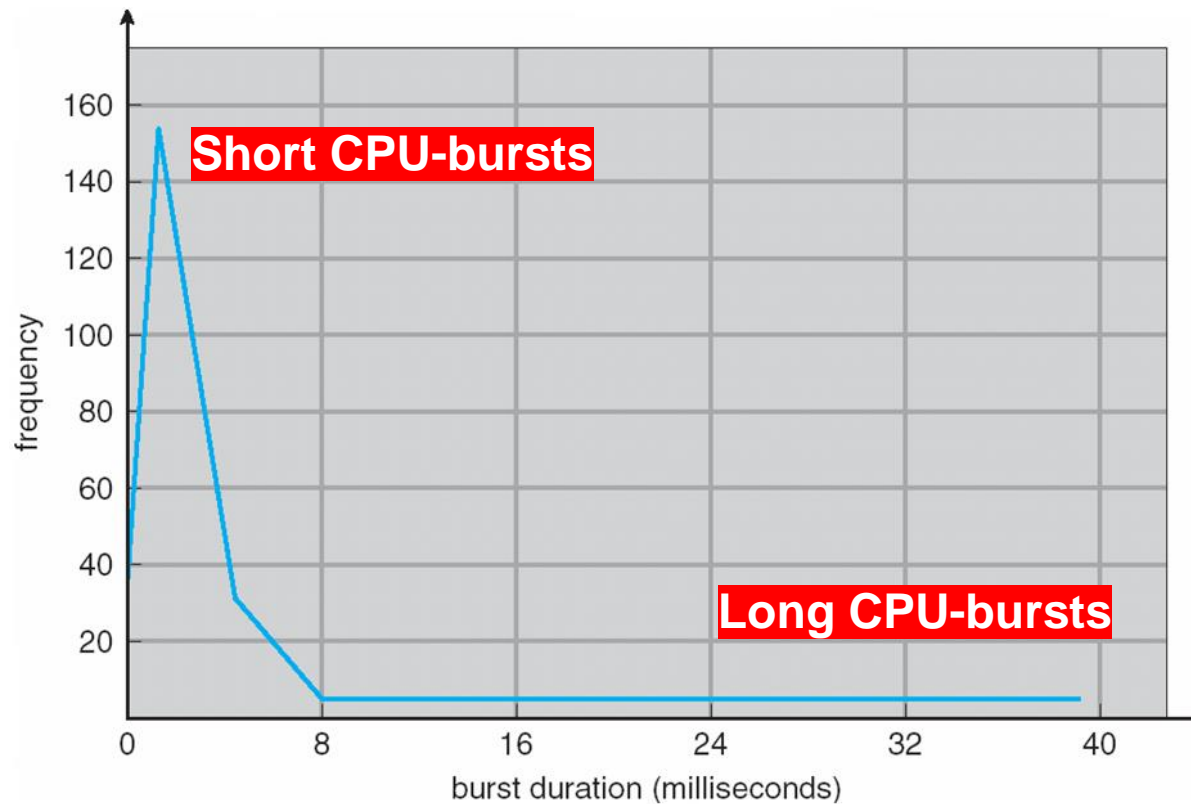
- Maximum CPU utilization obtained with multiprogramming
- CPU-I/O Burst Cycle – Process execution consists of a **cycle** of CPU execution and I/O wait
- **CPU burst** followed by **I/O burst**
- CPU burst distribution is of main concern





# Histogram of CPU-burst Times

- An I/O-bound program typically has many short CPU bursts.
- A CPU-bound program might have a few long CPU bursts.





# CPU Scheduler

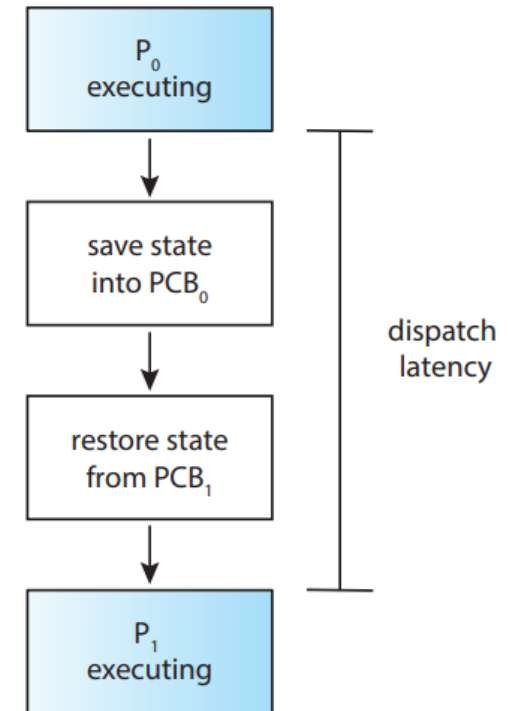
- **Short-term scheduler** selects from among the processes in ready queue, and allocates the CPU to one of them
  - Queue may be ordered in various ways
- CPU scheduling decisions may take place when a process:
  1. **Switches from running to waiting state**
  2. Switches from running to ready state
  3. Switches from waiting to ready
  4. **Terminates**
- Scheduling under 1 and 4 is **nonpreemptive**
- All other scheduling is **preemptive**
  - Consider access to shared data
  - Consider preemption while in kernel mode
  - Consider interrupts occurring during crucial OS activities





# Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the short-term scheduler; this involves:
  - switching context
  - switching to user mode
  - jumping to the proper location in the user program to restart that program
- **Dispatch latency** – time it takes for the dispatcher to stop one process and start another running





# Scheduling Criteria

- **CPU utilization** – keep the CPU as busy as possible
- **Throughput** – # of processes that complete their execution per time unit
- **Turnaround time** – amount of time to execute a particular process
  - **TAT = CT - AT**
- **Waiting time** – amount of time a process has been waiting in the ready queue
  - **WT = CT - AT - BT**
  - **WT = TAT - BT**
- **Response time** – amount of time it takes from when a request was submitted until the first response is produced, not output (for time-sharing environment)
  - **RT = (The first time to be executed by CPU) - AT**

**Completion Time (CT):** This is the time when the process completes its execution.

**Arrival Time (AT):** This is the time when the process has arrived in the ready state.

**Burst Time (BT):** This is the time required by the process for its execution.







# Scheduling Algorithm Optimization Criteria

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- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time

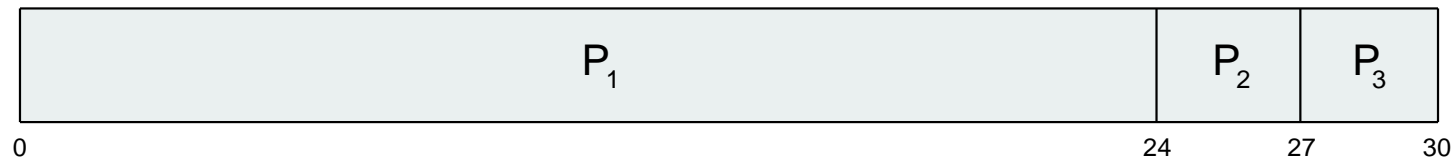




# First- Come, First-Served (FCFS) Scheduling

<u>Process</u>	<u>Burst Time</u>
$P_1$	24
$P_2$	3
$P_3$	3

- Suppose that the processes arrive in the order:  $P_1, P_2, P_3$   
The Gantt Chart for the schedule is:



- Waiting time for  $P_1 = 0$ ;  $P_2 = 24$ ;  $P_3 = 27$
- Average waiting time:  $(0 + 24 + 27)/3 = 17$





# First- Come, First-Served (FCFS) Scheduling



- Turnaround Time for  $P_1 = 24$ ;  $P_2 = 27$ ;  $P_3 = 30$
- Average Turnaround Time :  $(24 + 27 + 30)/3 = 30$





# First- Come, First-Served (FCFS) Scheduling

<u>Process</u>	<u>Arrive Time</u>	<u>Burst Time</u>
$P_1$	0	24
$P_2$	1	3
$P_3$	2	3

□



- **Turnaround Time** for  $P_1 = 24-0$ ;  $P_2 = 27-1$ ;  $P_3 = 30-2$
- **Average Turnaround Time:**  $(24 + 26 + 28)/3 = 26$





# FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_2, P_3, P_1$$

- The Gantt chart for the schedule is:



- Waiting time for  $P_1 = 6$ ;  $P_2 = 0$ ;  $P_3 = 3$
- Average waiting time:  $(6 + 0 + 3)/3 = 3$
- Much better than previous case
- **Convoy effect** - short process behind long process
  - all the other processes wait for the one big process to get off the CPU.
  - results in lower CPU and device utilization than might be possible if the shorter processes were allowed to go first.
  - consider one CPU-bound and many I/O-bound processes





# Shortest-Job-First (SJF) Scheduling

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- Associate with each process the length of its next CPU burst
  - Use these lengths to schedule the process with the shortest time
- SJF is optimal – gives minimum average waiting time for a given set of processes
  - The difficulty is knowing the length of the next CPU request
  - Could ask the user

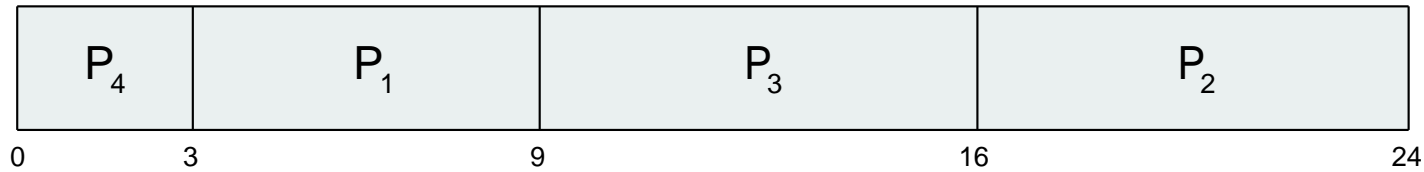




# Example of SJF

<u>Process</u>	<u>Burst Time</u>
$P_1$	6
$P_2$	8
$P_3$	7
$P_4$	3

- SJF scheduling chart



- Average waiting time =  $(3 + 16 + 9 + 0) / 4 = 7$
- **Turnaround Time** for  $P_1 = 9$  ;  $P_2 = 24$ ;  $P_3 = 16$ ;  $P_4 = 3$
- **Average Turnaround Time**:  $(9+24+16+3)/4 = 13$
- **What is the average waiting time using FCFS scheduling ?**





# Determining Length of Next CPU Burst

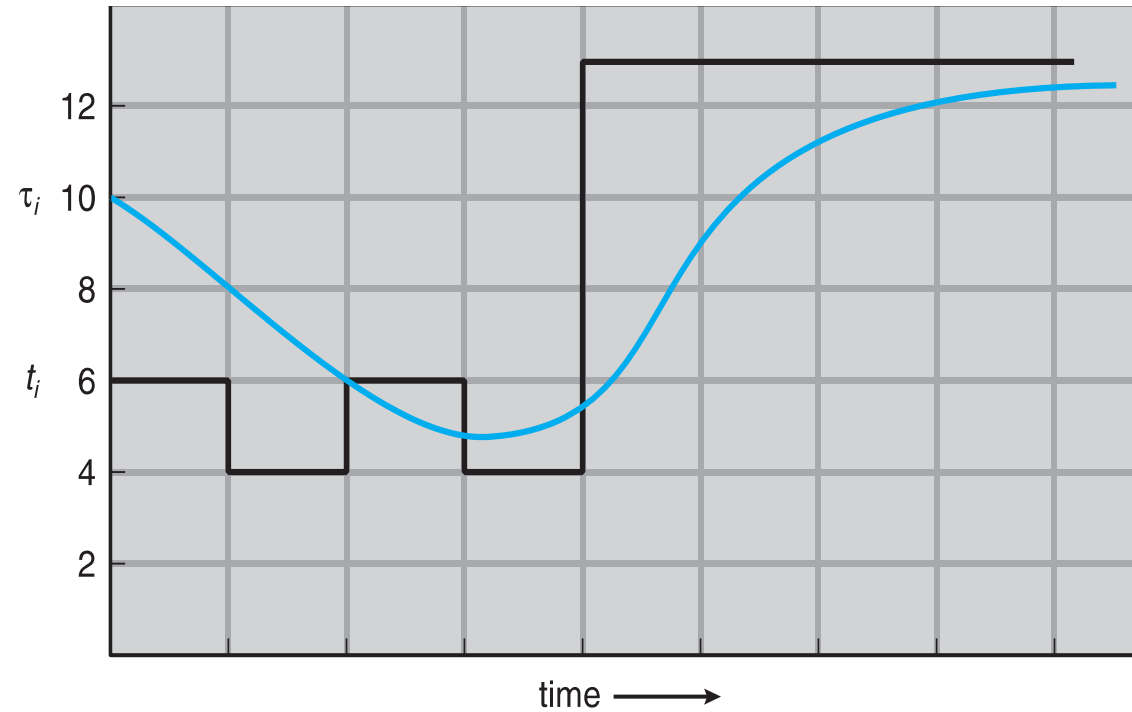
- Can only estimate the length – should be similar to the previous one
  - Then pick process with shortest predicted next CPU burst
  
- Can be done by using the length of previous CPU bursts, using exponential averaging
  1.  $t_n$  = actual length of  $n^{\text{th}}$  CPU burst
  2.  $\tau_{n+1}$  = predicted value for the next CPU burst
  3.  $\alpha, 0 \leq \alpha \leq 1$
  4. Define:  $\tau_{n+1} = \alpha t_n + (1 - \alpha)\tau_n$ .
  
- Commonly,  $\alpha$  set to  $\frac{1}{2}$
- Preemptive version called **shortest-remaining-time-first**







# Prediction of the Length of the Next CPU Burst



CPU burst ( $t_i$ )	6	4	6	4	13	13	13	...	
"guess" ( $\tau_i$ )	10	8	6	6	5	9	11	12	...

**Prove that diagram !!!**





# Examples of Exponential Averaging

- $\alpha = 0$ 
  - $\tau_{n+1} = \tau_n$
  - Recent history does not count
- $\alpha = 1$ 
  - $\tau_{n+1} = \alpha t_n$
  - Only the actual last CPU burst counts

- If we expand the formula, we get:

$$\begin{aligned}\tau_{n+1} = & \alpha t_n + (1 - \alpha)\alpha t_{n-1} + \dots \\ & + (1 - \alpha)^j \alpha t_{n-j} + \dots \\ & + (1 - \alpha)^{n+1} \tau_0\end{aligned}$$

- Since both  $\alpha$  and  $(1 - \alpha)$  are less than or equal to 1, each successive term has less weight than its predecessor



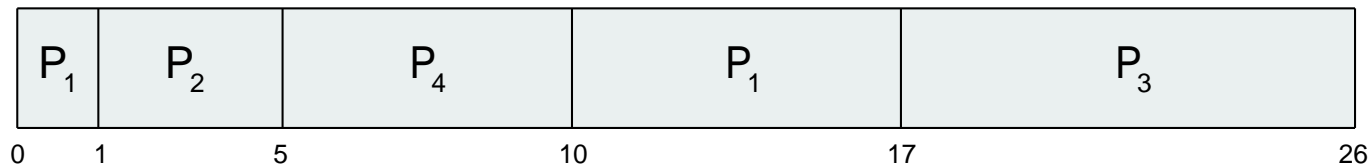


# Example of Shortest-remaining-time-first

- Now we add the concepts of varying arrival times and preemption to the analysis

<u>Process</u>	<u>Arrival Time</u>	<u>Burst Time</u>
$P_1$	0	8
$P_2$	1	4
$P_3$	2	9
$P_4$	3	5

- Preemptive SJF* Gantt Chart



- Average waiting time =  $[(10-1)+(1-1)+(17-2)+5-3]/4 = 26/4 = 6.5$  msec
- Turnaround Time** for  $P_1 = 17-0$  ;  $P_2 = 5-1$  ;  $P_3 = 26-2$  ;  $P_4 = 10-3$
- Average Turnaround Time:**  $(17+4+24+7)/4$





# Priority Scheduling

- A priority number (integer) is associated with each process
- The CPU is allocated to the process with the highest priority (smallest integer  $\equiv$  highest priority)
  - Preemptive
  - Nonpreemptive
- SJF is priority scheduling where priority is the inverse of predicted next CPU burst time
- Problem  $\equiv$  **Starvation** – low priority processes may never execute
- Solution  $\equiv$  **Aging** – as time progresses increase the priority of the process

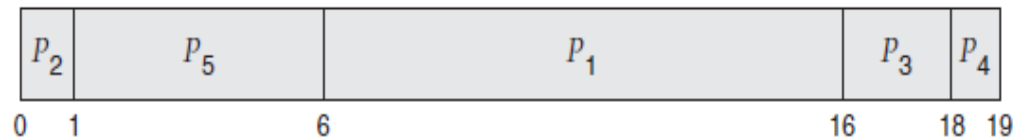




# Example of Priority Scheduling

<u>Process</u>	<u>Burst Time</u>	<u>Priority</u>
$P_1$	10	3
$P_2$	1	1
$P_3$	2	4
$P_4$	1	5
$P_5$	5	2

- Priority scheduling Gantt Chart



- **What is the** Average waiting time = 8.2 msec
- **The average waiting time using FCFS and SJF?**





# Round Robin (RR)

- Each process gets a small unit of CPU time (**time quantum**  $q$ ), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are  $n$  processes in the ready queue and the time quantum is  $q$ , then each process gets  $1/n$  of the CPU time in chunks of at most  $q$  time units at once. No process waits more than  $(n-1)q$  time units.
- Timer interrupts every quantum to schedule next process
- Performance
  - $q$  large  $\Rightarrow$  FIFO
  - $q$  small  $\Rightarrow$   $q$  must be large with respect to context switch, otherwise overhead is too high

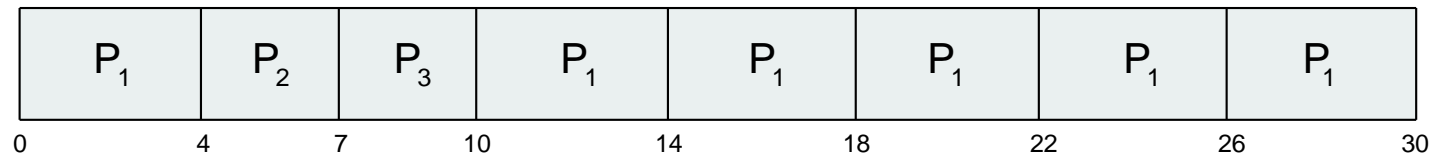




# Example of RR with Time Quantum = 4

<u>Process</u>	<u>Burst Time</u>
$P_1$	24
$P_2$	3
$P_3$	3

□ The Gantt chart is:

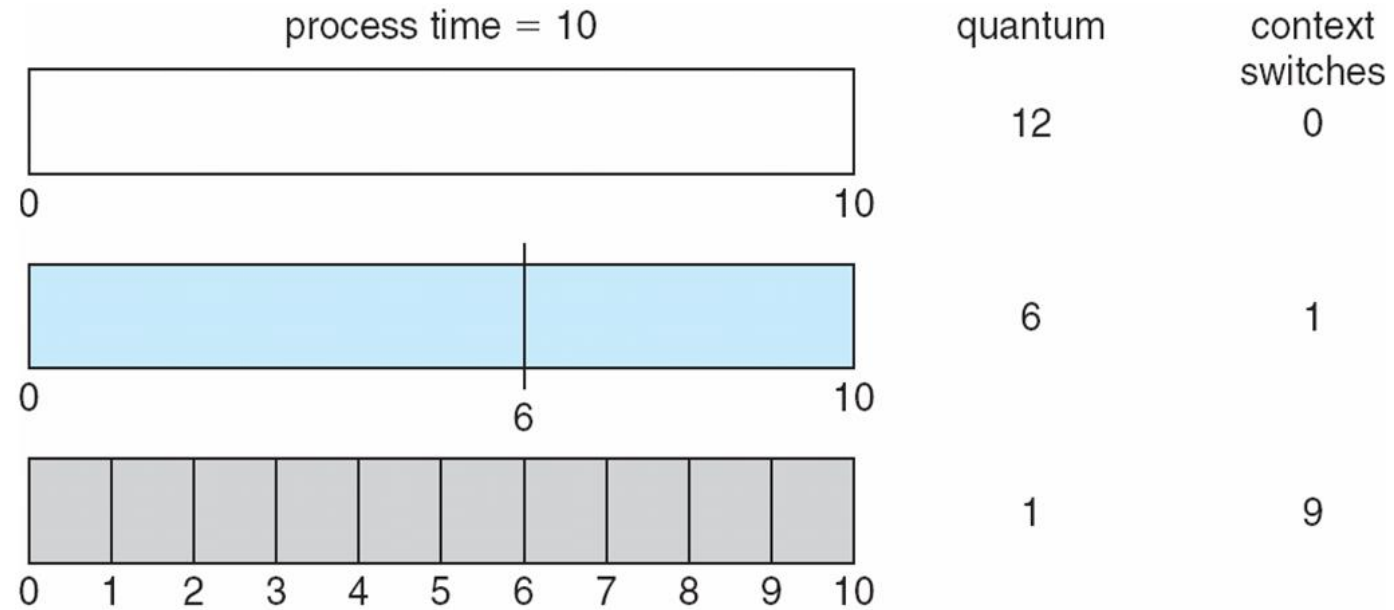


- Average turnaround time =  $(30 + 7 + 10) / 3 = 15.67$  msec
- Typically, **higher average turnaround time** than SJF, but better **response**
- q should be large compared to context switch time
- q usually 10ms to 100ms, context switch < 10 usec





# Time Quantum and Context Switch Time





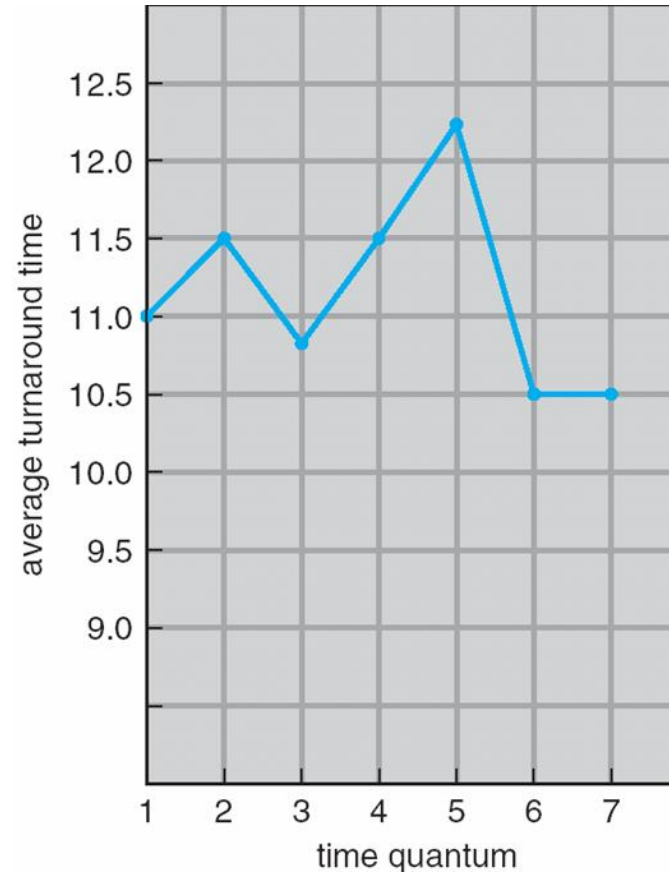


# Turnaround Time Varies With The Time Quantum

For  $Q=1$   
Average turn around time = 11 msec  
(prove)

For  $Q=5$   
Average turn around time = 12.25 msec (prove)

and so on.



process	time
$P_1$	6
$P_2$	3
$P_3$	1
$P_4$	7

80% of CPU bursts should be shorter than  $q$





# Preemptive/ Non preemptive

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Scheduling	Preemptive/ nonpreemptive
FCFS	nonpreemptive
SJF	may be either preemptive/ nonpreemptive
Priority	may be either preemptive/ nonpreemptive
RR	preemptive





# Multilevel Queue

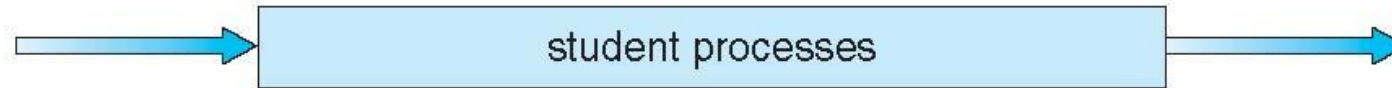
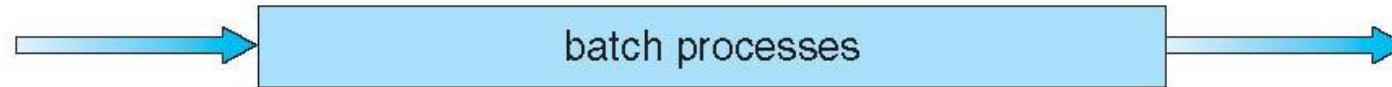
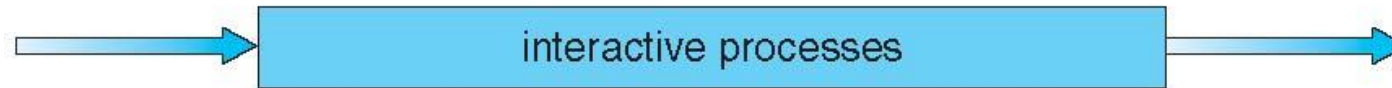
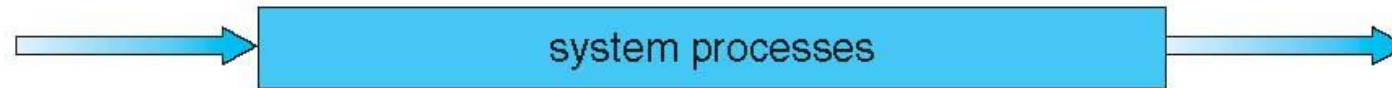
- Ready queue is partitioned into separate queues, eg:
  - **foreground** (interactive)
  - **background** (batch)
- Process permanently in a given queue
- Each queue has its own scheduling algorithm:
  - foreground – RR
  - background – FCFS
- Scheduling must be done between the queues:
  - Fixed priority scheduling; (i.e., serve all from foreground then from background). Possibility of starvation.
  - Time slice – each queue gets a certain amount of CPU time which it can schedule amongst its processes; i.e., 80% to foreground in RR
  - 20% to background in FCFS





# Multilevel Queue Scheduling

highest priority



lowest priority





# Multilevel Feedback Queue

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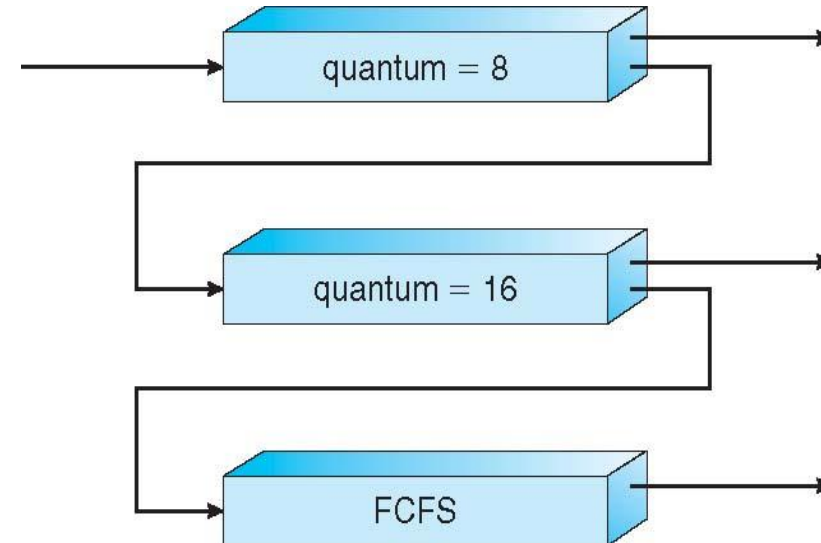
- A process can move between the various queues; aging can be implemented this way
- Multilevel-feedback-queue scheduler defined by the following parameters:
  - number of queues
  - scheduling algorithms for each queue
  - method used to determine when to upgrade a process
  - method used to determine when to demote a process
  - method used to determine which queue a process will enter when that process needs service





# Example of Multilevel Feedback Queue

- Three queues:
  - $Q_0$  – RR with time quantum 8 milliseconds
  - $Q_1$  – RR time quantum 16 milliseconds
  - $Q_2$  – FCFS
  
- Scheduling
  - A new job enters queue  $Q_0$  which is served FCFS
    - ▶ When it gains CPU, job receives 8 milliseconds
    - ▶ If it does not finish in 8 milliseconds, job is moved to queue  $Q_1$
  - At  $Q_1$  job is again served FCFS and receives 16 additional milliseconds
    - ▶ If it still does not complete, it is preempted and moved to queue  $Q_2$



# End of Chapter 6

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