

# Machine Learning (ML) with Python

## Artificial Neural Network (Deep Learning)

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#### Outline

- What is Deep Learning (DL) ?
- How do our brains work?
- Artificial Neural Network: *what is it*?
- How do ANNs work?
- Model of an artificial neuron
- NN Hidden Layers and Learning
- Learning by *trial* and *error*

- Main Issues in Designing NN
  - Activation Functions
    - Sigmoid
    - o *ReLU*
  - Error Estimation
  - Weights Adjusting
  - o Back Propagation
  - Number of Neurons
  - o Data Representation
  - Size of Training-set
- Learning Paradigms or Approaches (*recall*)
- Advantages / Disadvantages
- Example: Voice Recognition

### What is Deep Learning (DL) ?

A machine learning subfield of learning **representations** of data. Exceptional effective at **learning patterns**. Deep learning algorithms attempt to learn (multiple levels of) representation by using a **hierarchy of multiple layers** If you provide the system **tons of information**, it begins to understand it and respond in useful ways.



https://www.xenonstack.com/blog/static/public/uploads/media/machine-learning-vs-deep-learning.png

### How do our brains work?

- The Brain is a massively parallel information processing system.
- Our brains are a huge network of processing elements. A typical brain contains a network of 10 billion neurons.





An artificial neural network consists of a pool of simple processing units which communicate by sending signals to each other over a large number of **weighted** connections.

- Models of the brain and nervous system
- Highly parallel
  - Process information much more like the brain than a serial computer
- Learning
- Very simple principles
- Very complex behaviours
- Applications
  - As powerful problem solvers
  - As biological models

#### The "building blocks" of neural networks are the neurons.

• In technical systems, we also refer to them as **units** or **nodes**.



#### **Basically, each neuron**

- receives **input** from many other neurons.
- changes its internal state (activation) based on the current input.
- sends **one output signal** to many other neurons, possibly including its input neurons (**recurrent network**).

#### An artificial neuron is an imitation of a human neuron



```
A neuron looks like this...

f(x) = m x + b

could also be represented like

y = f(x)

f(x) = w1 * x1 + b

where w is the weight, and b is the bias
```

```
A general form to represent a neuron is:

y = f(x1 \cdot w1 + x2 \cdot w2 + ... + b)
```



The trick of machine learning is to find values of w and b coefficients (degree) that bring the best final results for the entire neuron network.

#### How do ANNs work?





**Activation functions** 

How do we train?

4 + 2 = 6 neurons (not counting inputs) [3 x 4] + [4 x 2] = 20 weights 4 + 2 = 6 biases

26 learnable **parameters** 

#### Model of an Artificial Neuron



### Model of an Artificial Neuron



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### Model of an Artificial Neuron



- The signal is not passed down to the next neuron directly.
- The output is a **function** of the input,
   that is affected by the weights, and
   the **activation functions**

#### **Feed-forward nets**



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#### NN hidden Layers and Learning



#### An ANN can:

- compute *any computable* function, by the appropriate selection of the network topology and weights values.
- learn from experience!
- Specifically, by trial-and-error

#### Weight settings determine the behavior of a network

How can we find the right weights?

#### **Training the Network - Learning**

- Backpropagation
  - Requires training set (input / output pairs)
  - Starts with small random weights
  - Error is used to adjust weights (supervised learning)
  - → Gradient descent on error landscape



#### For Example:



### Learning by trial-and-error

#### Continuous process of

#### • Trial:

 Processing an input to produce an output (In terms of ANN: Compute the output function of a given input)

#### Evaluate:

- $\circ$  Evaluating this output by comparing the actual output with the expected output.
- Adjust:
  - Adjust the weights.

# Main issues in designing NN

- Initial weights
- Activation (Transfer) function (How the inputs and the weights are combined to produce output?)
- Error estimation
- Weights adjusting
- Number of neurons
- Data representation
- Size of training set



- Linear: The output is proportional to the total weighted input.
- Threshold: The output is set at one of two values, depending on whether the total weighted input is greater than or less than some threshold value.
- Non-linear: The output varies continuously but not linearly as the input changes.

#### **Activation Functions**

Non-linearities needed to learn complex (non-linear) representations of data, otherwise the NN would be just a linear function  $y = f(x1 \cdot w1 + x2 \cdot w2 + ... + b)$ 



http://cs231n.github.io/assets/nn1/layer\_sizes.jpeg

More layers and neurons can approximate more complex functions

### **Activation: Sigmoid**

- + Nice interpretation as the **firing rate** of a neuron
  - 0 = not firing at all
  - 1 = fully firing
- Sigmoid neurons stick or kill gradients, thus NN will hardly learn
  - when the neuron's activation are 0 or 1 (stick)
    - gradient at these regions almost zero
    - $\circ$  almost no signal will flow to its weights
    - if initial weights are too large then most neurons would stick

Takes a real-valued number and "squashes" it into range between 0 and 1.



### Activation: ReLU

Most Deep Networks use ReLU nowadays

- ① Trains much **faster**
- ① Less expensive operations
  - compared to sigmoid/tanh (exponentials etc.)
  - implemented by simply thresholding a matrix at zero
- (1) More **expressive**
- (:) Prevents the gradient vanishing problem

Takes a real-valued number and thresholds it at zero f(x) = max(0, x)



http://adilmoujahid.com/images/activation.png

#### **Error Estimation**

#### The root mean square error (RMSE)

is a frequently-used measure of the differences between values predicted by a model or an estimator and the values actually observed from the thing being modelled or estimated.

#### Weights Adjusting

After each iteration, weights should be adjusted to minimize the error.

- All possible weights
- Back propagation

### **Back Propagation**

• Back-propagation is an example of supervised learning is used at each layer to minimize the error

between the layer's response and the actual data

- The error at each hidden layer is an average of the evaluated error
- Hidden layer networks are trained this way.
- The poplar algorithm used here is *gradient descent*.



## **Back Propagation**

- N is a neuron.
- N<sub>w</sub> is one of N's inputs weights
- N<sub>out</sub> is N's output.
- $N_w = N_w \alpha \nabla N_w$
- $\nabla N_w = N_{out} * (1 N_{out}) * N_{ErrorFactor}$
- $N_{ErrorFactor} = N_{ExpectedOutput} N_{ActualOutput}$

This works only for the last layer, as we can know the actual output, and the expected output.

### Number of neurons

- Many neurons:
  - Higher accuracy
  - Slower
  - Risk of over-fitting
    - Memorizing, rather than understanding
    - The network will be useless with new problems.
- Few neurons:
  - Lower accuracy
  - Inability to learn at all
- Optimal number!

#### **Data Representation**

- Usually input/output data needs pre-processing
- Pictures
  - Pixel intensity
- Text:
  - > A pattern
    - 0-0-1 for "Asma" 0-1-0 for "Abrar"
  - Encoding mechanism

# Size of Training-set

• Overfitting can occur if a "good" training set is not chosen



- What constitutes a "good" training set?
  - Samples must represent the general population.
  - Samples must contain members of each class.
  - Samples in each class must contain a wide range of variations or noise effect.
- The size of the training set is <u>related</u> to the number of hidden neurons

#### Learning Paradigms (recall)

- <u>Supervised learning (our focus on this lecture)</u>
- Unsupervised learning
- Reinforcement learning

#### Advantages / Disadvantages

#### • Advantages

- Adapt to unknown situations
- Powerful, it can model complex functions.
- Ease of use, learns by example, and very little user domain-specific expertise needed

#### • Disadvantages

- Not exact
- Large complexity of the network structure

#### **Example: Voice Recognition**

- Task: Learn to differentiate between two different voices saying "Hello"
- Data
  - Sources
    Steve
  - > David
  - Format
    - Frequency distribution (60 bins)



#### Network architecture

#### Feed forward network

- > 60 input (one for each frequency bin)
- > 1 hidden with 6 neurons
- > 2 output (0-1 for "Steve", 1-0 for "David")



### Presenting the data



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#### Presenting the data (untrained network)



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#### **Calculate error**



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#### Backprop error and adjust weights



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### Backprop error and adjust weights

- Repeat process (sweep) for all training pairs
  - Present data
  - Calculate error
  - Backpropagate error
  - Adjust weights
- Repeat process multiple times



#### Presenting the data (trained network)



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#### **Results – Voice Recognition**

Performance of trained network

- Recognition accuracy between known "Hello"s
  - <u>100%</u>
- Recognition accuracy between new "Hello"'s
  - <u>100%</u>

# Any questions?